Graduate Program in Acoustics Department of Mechanical Engineering The University of Texas at Austin

### **Introduction to Aeroacoustics**

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## Plan

### • Recap on linear acoustics

- Linearized conservation equations
- Near- & far-field
- Acoustical compactness
- Acoustical energy and flow-acoustic resonances
- Green's function and integral solutions
- Introduction to aeroacoustical analogies
  - Lighthill's analogy
    - M<sup>8</sup> law
    - Choice of the acoustical variable
  - Curle's analogy and non-compact sources
    - Aeolian tone
  - Ffowcs Williams & Hawkings analogy
    - Application to fan noise

## **Continuity equation**

### • For an infinitesimal fluid particle:



## **Momentum equation**



## Linearization

• Continuity and momentum equations:



• Perturbations = deviations with respect to uniform and stagnant fluid:  $\rho = \rho_0 + \rho'$ 

$$p = p_0 + p'$$
$$\mathbf{v} = \mathbf{v}_0 + \mathbf{v}' = \mathbf{v}'$$

At first order, the continuity and momentum equations become:

$$\frac{\partial \rho'}{\partial t} + \rho_0 \,\nabla \cdot \mathbf{v}' = Q_{\rm m} \qquad \rho_0 \,\frac{\partial \mathbf{v}'}{\partial t} = -\nabla p' + \nabla \cdot \boldsymbol{\sigma}' + \mathbf{f}$$

## **Acoustic sources**

• Eliminate  $\mathbf{v}'$  from the linearized conservation equations:

$$\frac{\partial}{\partial t} \left\{ \frac{\partial \rho'}{\partial t} + \rho_0 \nabla \cdot \mathbf{v}' = Q_m \right\}$$
$$-\nabla \cdot \left\{ \rho_0 \frac{\partial \mathbf{v}'}{\partial t} = -\nabla p' + \nabla \cdot \boldsymbol{\sigma}' + \mathbf{f} \right\}$$

$$\frac{\partial^2 \rho'}{\partial t^2} - \nabla^2 p' = -\nabla \cdot \mathbf{f} - \nabla \cdot (\nabla \cdot \boldsymbol{\sigma}') + \frac{\partial Q_m}{\partial t}$$

more unknowns than equations...

## Linearized constitutive equation

• Equation of state:  $p = p(\rho, s)$ 

• Perturbation: 
$$p' = \left(\frac{\partial p}{\partial \rho}\right)_s \rho' + \left(\frac{\partial p}{\partial s}\right)_\rho s'$$

• Definition of the speed of sound:  $c_0^2 \equiv \left(\frac{\partial p}{\partial \rho}\right)_a$ 

$$\qquad p' = c_0^2 \rho' + \left(\frac{\partial p}{\partial s}\right)_{\rho} s'$$

## **Sources of sound**



Mass source is used as model for entropy production. We assume iso-kinetic injection (no momentum source) and isentropic process.

## Monopoles, dipoles, quadrupoles

- Monopole = pulsating sphere, jumping in a boat
- Physically: unsteady combustion, pipe exhaust, vocal folds, ...
- Dipole = oscillating sphere, playing with a ball in a boat
- Less efficient than monopole
- Physically: unsteady forces
- Quadrupole = deforming sphere without change of volume nor net force, fighting in a boat!
- Less efficient than dipole
- Physically: turbulence





## **Spherical waves**

• Homogeneous wave propagation equation in spherical coordinates:

$$\frac{1}{c_0^2} \frac{\partial^2(rp')}{\partial t^2} - \frac{\partial^2(rp')}{\partial r^2} = 0$$

• Same solution as in 1D using rp' as unknown:

$$rp' = f\left(t - \frac{r}{c_0}\right) + g\left(t + \frac{r}{c_0}\right)$$
  
Outgoing wave Incoming wave

 $|\mathbf{x}|$ 

• In frequency domain:

$$p' = \frac{A}{r} \exp\left(i\omega\left(t - \frac{r}{c_0}\right)\right) = \frac{A}{r} \exp\left(i\left(\omega t - kr\right)\right)$$

## **Far-field and near-field**

• Linearized momentum equation in spherical coordinates:

• Two regimes:

• Far-field: 
$$\lim_{kr\to\infty} v'_r = \frac{p'}{\rho_0 c_0} \propto \frac{1}{r}$$

Plane wave behaviour

• Near-field: 
$$\lim_{kr \to 0} v'_r = \frac{p'}{\mathrm{i}\omega\rho_0 r} \propto \frac{1}{r^2}$$

Locally incompressible flow

## **Acoustical compactness**

• Upon normalization using the length scale L and the time scale  $\tau$ :  $\tilde{t} \equiv t/\tau$   $\tilde{x}_i \equiv x_i/L$ 

the wave propagation equation 
$$\frac{\partial^2 \varphi'}{\partial t^2} - c_0^2 \frac{\partial^2 \varphi'}{\partial x_i^2} = 0$$

becomes:  $\frac{\partial^2 \varphi'}{\partial \tilde{x}_i^2} = \left(\frac{L}{c_0 \tau}\right)$ 

$$\frac{1}{2} \int^2 \frac{\partial^2 \varphi'}{\partial \tilde{t}^2} = He^2 \frac{\partial^2 \varphi'}{\partial \tilde{t}^2}$$

with Helmholtz number  $He \equiv \frac{L}{c_0 \tau} = \frac{\omega L}{c_0} = \frac{2\pi L}{\lambda} = kL$ 

• Compact region:  $He \ll 1 \Rightarrow \nabla^2 \varphi' = 0$  Laplace equation

At low Helmholtz numbers, i.e. in a compact region, the wave propagation equation reduces to the Laplace equation, describing an <u>incompressible potential</u> flow

Corollary: an incompressible potential flow model solves the "acoustics problem" in a compact region

## **Acoustical energy**

• Manipulating linearized conservation equations:

$$\frac{p'}{\rho_0} \left\{ \frac{\partial \rho'}{\partial t} + \rho_0 \, \nabla \cdot \mathbf{v}' = Q_{\rm m} \right\} \\ + \mathbf{v}' \cdot \left\{ \rho_0 \, \frac{\partial \mathbf{v}'}{\partial t} = -\nabla p' + \nabla \cdot \boldsymbol{\sigma}' + \mathbf{f} \right\} \\ \frac{\partial \rho_0}{\partial t} \underbrace{\left( \frac{1}{2} \, \rho_0 \, (\mathbf{v}')^2 + \frac{1}{2} \frac{p'^2}{\rho_0 c_0^2} \right)}_{E} + \nabla \cdot \underbrace{\left( p' \mathbf{v}' \right)}_{\mathbf{I}} = \mathbf{v}' \cdot \mathbf{f} + \frac{p'}{\rho_0 c_0^2} \left( \frac{\partial p}{\partial s} \right)_{\rho} \frac{\partial s'}{\partial t} + \frac{p' Q_{\rm m}}{\rho_0}$$

## **Acoustical energy and intensity**



# Integral formulation for steady harmonic oscillations



## Free field Green's function in 3 dimensions

• Inhomogeneous wave equation:

$$\frac{\partial^2 G}{\partial t^2} - c_0^2 \nabla^2 G = \mathbf{\delta}(\mathbf{x} - \mathbf{y}) \,\mathbf{\delta}(t - \tau)$$



- Important properties:
  - Dirac function  $\rightarrow$  convenient to obtain an integral solution

• Reciprocity: 
$$G(\mathbf{x}, t | \mathbf{y}, \tau) = G(\mathbf{y}, -\tau | \mathbf{x}, -t)$$

## Solution of the wave equation based on Green's function

$$\left\{\frac{\partial^2 \rho'}{\partial t^2} - c_0^2 \nabla^2 \rho' = q(\mathbf{x}, t)\right\} \quad \times G, \iiint_V, \int_{t_0}^t$$

$$-\left\{\frac{\partial^2 G}{\partial t^2} - c_0^2 \nabla^2 G = \mathbf{\delta}(\mathbf{x} - \mathbf{y}) \,\mathbf{\delta}(t - \tau)\right\} \quad \times \rho', \iiint_V, \int_{t_0}^t$$

$$\rho'(\mathbf{x},t) = \int_{t_0}^t \iiint_V q(\mathbf{y},\tau) G(\mathbf{x},t|\mathbf{y},\tau) \, \mathrm{d}^3 \mathbf{y} \mathrm{d}\tau + \int_{t_0}^t \iiint_V \left( \rho'(\mathbf{y},\tau) \frac{\partial^2 G}{\partial \tau^2} - G \frac{\partial^2 \rho'(\mathbf{y},\tau)}{\partial \tau^2} \right) \, \mathrm{d}^3 \mathbf{y} \mathrm{d}\tau - c_0^2 \int_{t_0}^t \iiint_V \left( \rho'(\mathbf{y},\tau) \frac{\partial^2 G}{\partial y_i^2} - G \frac{\partial^2 \rho'(\mathbf{y},\tau)}{\partial y_i^2} \right) \, \mathrm{d}^3 \mathbf{y} \mathrm{d}\tau$$

## Integral solution of the wave equation

• Integrating by parts: 
$$\rho'(\mathbf{x}, t) = \int_{t_0}^t \iiint_V q(\mathbf{y}, \tau) G(\mathbf{x}, t | \mathbf{y}, \tau) d^3 \mathbf{y} d\tau$$
  
 $- \left[\iiint_V \left(\rho'(\mathbf{y}, \tau) \frac{\partial G}{\partial \tau} - G \frac{\partial \rho'(\mathbf{y}, \tau)}{\partial \tau}\right) d^3 \mathbf{y}\right]_{\tau=t_0}$   
• Further simplifications:  $-c_0^2 \int_{t_0}^t \iint_S \left(\rho'(\mathbf{y}, \tau) \frac{\partial G}{\partial y_i} - G \frac{\partial \rho'(\mathbf{y}, \tau)}{\partial y_i}\right) n_i d^2 \mathbf{y} d\tau$ 

- Silent initial conditions, causality
- No solid surface, OR: non-vibrating surfaces and tailored Green's fuction

$$\rho'(\mathbf{x},t) = \int_{t_0}^t \iiint_V q(\mathbf{y},\tau) G(\mathbf{x},t|\mathbf{y},\tau) \, \mathrm{d}^3 \mathbf{y} \mathrm{d}\tau$$

Having an integral formulation improves the numerical stability of the prediction when detailed flow data (e.g. LES) are available, and otherwise permits deriving scaling laws!

## **Other Green's functions**

- In a few cases: analytical Green's functions
  - Infinite planes: image sources (semi-anechoic environment)
  - Semi-infinite plane (trailing edge noise)
  - Infinite straight ducts: rectangular, cylindrical, annular
- In other cases: semi-analytical Green's functions
  - Compact (low-frequency) Green's functions (Howe)
  - Wiener-Hopf technique, Schwarzchild's technique (TE-LE backscattering, Roger)
  - Slowly-varying duct (Rienstra)
- In all other cases: numerical Green's functions
  - Low-frequency techniques
    - Finite Element Methods, Boundary Element Methods
  - High-frequency techniques
    - Ray-tracing methods, Statistical Energy Analysis
  - Mid-frequency techniques
    - Multigrid techniques, fast multipole BEM, ...

## **Summary**

- Assuming small amplitude acoustic perturbations, the equations of fluid motion can be linearized and used to derive a wave equation for these perturbations.
- The relationship between the perturbations are given by the linearized momentum equation and the linearized constitutive equation:

$$\rho_0 \frac{\partial \mathbf{v}'}{\partial t} = -\nabla p' \qquad \qquad p' = c_0^2 \rho' + \left(\frac{\partial p}{\partial s}\right)_{\rho} s'$$

- In the linear approximation, the sources of the acoustic field can be due to
  - Unsteady mass injection or entropy fluctuations  $\rightarrow$  monopolar character.
  - Non-uniform forces  $\rightarrow$  dipolar character.
  - Fluctuating viscous stresses (and, later, Reynolds stresses) → quadrupolar character.
- Each of these sources has a different radiation efficiency in free field.
- The sound radiation is determined by the source and the impedance which it experiences!
- An integral formulation of the wave equation can be obtained using Green's functions, which enhances the numerical robustness of the prediction.

### Aeroacoustic analogies: why ?

- Acoustic field = part of the flow field 
   most straightforward approach: Computational AeroAcoustics (CAA)
  - But: at low Mach numbers: orders of magnitude of difference between
    - Length scales:  $\lambda_{ac} = L_{turb} / M$
    - Magnitudes: O(M<sup>4</sup>) of the flow energy radiates into the far field



- High order schemes needed to capture acoustic propagation
- Numerical cost of a direct CAA scales with Re<sup>2</sup> M<sup>-4</sup> for a Large Eddy Simulation
- Specific issues related to CFD discretisation techniques applied to acoustics
  - Dissipation and dispersion errors
  - Initial and boundary conditions

# Lighthill's aeroacoustical analogy : concept

- The problem of sound produced by a turbulent flow is, from the listener's point of view, analogous to a problem of propagation in a uniform medium at rest in which equivalent sources are placed.
- Wave propagation region: linear
   wave operator applies

No source

$$\frac{\partial^2 \rho'}{\partial t^2} - c_0^2 \frac{\partial^2 \rho'}{\partial x_i^2} = 0$$



• Turbulent region: fluid mechanics equations apply

 $\frac{\frac{\text{mass}}{\partial \rho}}{\frac{\partial \rho}{\partial t} + \frac{\partial \rho v_i}{\partial x_i}} = 0 \qquad \frac{\frac{\partial \rho v_i}{\partial t}}{\frac{\partial \rho}{\partial t}} + \frac{\frac{\partial \rho v_i v_j}{\partial x_j}}{\frac{\partial \rho v_i v_j}{\partial x_j}} = -\frac{\frac{\partial \Pi_{ij}}{\partial x_j}}{\frac{\partial \sigma}{\partial t}}$ 

## Lighthill's analogy: formal derivation

$$\frac{\partial}{\partial t} \left\{ \frac{\partial \rho}{\partial t} + \frac{\partial \rho v_i}{\partial x_i} = 0 \right\} \qquad \text{Continuity}$$
$$-\frac{\partial}{\partial x_i} \left\{ \frac{\partial \rho v_i}{\partial t} + \frac{\partial \rho v_i v_j}{\partial x_j} = -\frac{\partial \Pi_{ij}}{\partial x_j} \right\} \qquad \text{Momentum}$$
$$\implies \qquad \frac{\partial^2 \rho}{\partial t^2} = \frac{\partial^2 (\rho v_i v_j - \sigma_{ij})}{\partial x_i \partial x_j} + \frac{\partial^2 p}{\partial x_i^2}$$

$$\frac{\partial^2 \rho}{\partial t^2} - \boxed{c_0^2 \frac{\partial^2 \rho}{\partial x_i^2}} = \frac{\partial^2 (\rho v_i v_j - \sigma_{ij})}{\partial x_i \partial x_j} + \frac{\partial^2 (p - c_0^2 \rho)}{\partial x_i^2}$$

# Lighthill's aeroacoustical analogy : reference state

• Reformulation of fluid mechanics equations, and use of arbitrary speed  $c_0$ :



with  $T_{ij} = \rho v_i v_j + (p' - c_0^2 \rho') \delta_{ij} - \sigma_{ij}$ Lighthill's tensor

#### Exact... and perfectly useless!

## Sound produced by free isothermal turbulent flows at low Mach number



• Using free field Green's fct  $G_0(t, \mathbf{x}|\tau, \mathbf{y}) = \frac{\delta(t - \tau - |\mathbf{x} - \mathbf{y}|/c_0)}{4\pi c_0^2 |\mathbf{x} - \mathbf{y}|}$ 

$$\rho'(\mathbf{x},t) = \frac{\partial^2}{\partial x_i \partial x_j} \iiint \left[ \frac{\rho_0 v_i v_j}{4\pi c_0^2 |\mathbf{x} - \mathbf{y}|} \right] \mathrm{d}^3 \mathbf{y}$$
 Quadrupolar source  $t^* = t - |\mathbf{x} - \mathbf{y}|/c_0$ 

## Lighthill's M<sup>8</sup> law

• Integral solution: 
$$\rho'(\mathbf{x}, t) = \frac{\partial^2}{\partial x_i \partial x_j} \iiint \left[ \frac{\rho_0 v_i v_j}{4\pi c_0^2 |\mathbf{x} - \mathbf{y}|} \right] d^3 \mathbf{y}$$
  
 $\mathbf{y} = t - |\mathbf{x} - \mathbf{y}|/c_0$ 

• Scaling law:



### **Choice of the aeroacoustical variable**

• Manipulating the mass and momentum equations yields:

$$\frac{\partial^2 \rho}{\partial t^2} = \frac{\partial^2}{\partial x_i \partial x_j} \left( \rho v_i v_j - \sigma_{ij} \right) + \frac{\partial^2 p}{\partial x_i^2}$$

- From there, two choices are possible for the acoustical variable:
  - Acoustical density perturbation:

$$\frac{\partial^2 \rho'}{\partial t^2} \left[ -c_0^2 \frac{\partial^2 \rho'}{\partial x_i^2} \right] = \frac{\partial^2}{\partial x_i \partial x_j} \left( \rho v_i v_j - \sigma_{ij} \right) + \frac{\partial^2}{\partial x_i^2} \left( p' \left[ -c_0^2 \rho' \right] \right)$$
 Isentropic noise generation

Acoustical pressure perturbation:

$$\underbrace{\frac{1}{c_0^2}\frac{\partial^2 p'}{\partial t^2}}_{i} - \frac{\partial^2 p'}{\partial x_i^2} = \frac{\partial^2}{\partial x_i \partial x_j} \left(\rho v_i v_j - \sigma_{ij}\right) + \frac{\partial^2}{\partial t^2} \left(\underbrace{\frac{p'}{c_0^2}}_{0} - \rho'\right) \qquad \begin{array}{c} \text{Combustion} \\ \text{noise} \end{array}$$

## **Curle's analogy: fixed rigid bodies**

- Lighthill's aeroacoustical analogy:  $\frac{\partial^2 \rho'}{\partial t^2} c_0^2 \frac{\partial^2 \rho'}{\partial x_i^2} = \frac{\partial^2 T_{ij}}{\partial x_i \partial x_j}$
- Integral solution using Green's function

$$\rho'(\mathbf{x},t) = \int_{-\infty}^{t} \iiint_{V} \frac{\partial^{2}T_{ij}}{\partial y_{i}\partial y_{j}} G d^{3}\mathbf{y}d\tau \quad \text{incident field}$$
$$-c_{0}^{2} \int_{-\infty}^{t} \iint_{\partial V} \left(\rho' \frac{\partial G}{\partial y_{i}} - G \frac{\partial \rho'}{\partial y_{i}}\right) n_{i} d^{2}\mathbf{y}d\tau$$
$$\text{scattered field}$$

• Partial integration of source integral

$$\int_{-\infty}^{t} \iiint_{V} \frac{\partial^{2} T_{ij}}{\partial y_{i} \partial y_{j}} G d^{3} \mathbf{y} d\tau = \int_{-\infty}^{t} \iiint_{V} T_{ij} \frac{\partial^{2} G}{\partial y_{i} \partial y_{j}} d^{3} \mathbf{y} d\tau + \int_{-\infty}^{t} \iint_{\partial V} \left\{ \left( -\frac{\partial \rho v_{i}}{\partial \tau} - \underline{c_{0}^{2}} \frac{\partial \rho'}{\partial y_{i}} \right) G - \left( \rho v_{i} v_{j} + (p' - \underline{c_{0}^{2}} \rho') \delta_{ij} + \sigma_{ij} \right) \frac{\partial G}{\partial y_{j}} \right\} n_{i} d^{2} \mathbf{y} d\tau$$

• Curle's analogy: uses free field Green's function  $G_0(t, \mathbf{x}|\tau, \mathbf{y}) = \frac{\delta(t - \tau - |\mathbf{x} - \mathbf{y}|/c_0)}{4\pi c_0^2 |\mathbf{x} - \mathbf{y}|}$ 

$$\implies \rho'(\mathbf{x},t) = \frac{\partial^2}{\partial x_i \partial x_j} \iiint_V \left[ \frac{T_{ij}}{4\pi c_0^2 |\mathbf{x} - \mathbf{y}|} \right] \, \mathrm{d}^3 \mathbf{y} - \frac{\partial}{\partial x_i} \iint_{\partial V} \left[ \frac{p' n_i}{4\pi c_0^2 |\mathbf{x} - \mathbf{y}|} \right] \, \mathrm{d}^2 \mathbf{y}$$

If you know the multipolar character of your source...







7.1: Left: one quadrupole  $T_{xy} = 1$ ; right: one quadrupole  $T_{xy} = 1.05$ .



7.2: Left: two dipoles with amplitudes  $D_{x,1-2} = \pm 200$  (left); right:  $D_{x,1} = 210$ ,  $D_{x,2} = 200$ .



# A popular formulation for industrial applications

- Curle's formulation is quite powerful
  - It enforces the correct radiation pattern of each source component:  $P_{quadru} / P_{dipo} \sim M^2$
  - At low Mach numbers, dipolar contribution dominates the quadrupolar one for compact sources
  - Surface scalar (p') data are much less demanding in memory than volumetric, tensorial (T<sub>ii</sub>) data
  - Surface mesh often available from design stage

$$4\pi c_0^2 \,\rho'(\mathbf{x},t) = \frac{\partial^2}{\partial x_i \partial x_j} \iiint_V \left[\frac{T_{ij}}{|\mathbf{x} - \mathbf{y}|}\right] \,\mathrm{d}^3 \mathbf{y} + \frac{\partial}{\partial x_i} \iint_{\partial V} \left[\frac{p' n_i}{|\mathbf{x} - \mathbf{y}|}\right] \,\mathrm{d}^2 \mathbf{y}$$

$$\begin{bmatrix} \mathbf{Quadrupole, W \propto M^8} \\ \text{in free field} \end{bmatrix} \quad \begin{bmatrix} \mathbf{Dipole, W \propto M^6} \\ \text{in free field} \end{bmatrix}$$

• BUT: tricky implementation for non-compact geometries...

### The hybrid approach from a practical viewpoint

- The computation of flow is decoupled from the computation of sound
  - Acoustic prediction: post-processing of source field data
- Fundamental assumption: one-way coupling
  - Unsteady flow produces sound and affects its propagation
  - BUT: sound waves do not affect flow field significantly
  - Principal application of the hybrid approach: flows at low Mach numbers
- Usable simulation tools for the flow description:
  - Reynolds Averaged Navier-Stokes (RANS) solver
     → time-averaged data (SNGR to reconstruct transient) ☺
  - Unsteady RANS → unsteady, but only large scale ☺
  - Large Eddy Simulation (LES), Detached Eddy Simulation (DES)
     → unsteady, broadband turbulence (up to grid & scheme cutoff frequency) ☺
- Low-Mach number applications
  - Incompressible LES / DES solvers to reduce CPU cost
  - Careful interpretation of the flow data in aeroacoustical analogy





http://www.lmfa.ec-lyon.fr/recherche/turbo

# Ffowcs Williams and Hawkings analogy: moving bodies

- Use of generalized functions to account for body motion
- Body motion trajectory described by function *F*(*x*,*y*,*z*,*t*):



• Heaviside and Dirac functions properties:

$$\begin{split} H(F) &= 0 & \text{inside solid body} \\ &= 1 & \text{in fluid region} \\ \nabla(H(F)) &= \delta(F) \, \nabla F \\ \frac{\partial}{\partial t}(H(F)) &= \delta(F) \, \frac{\partial F}{\partial t} \end{split}$$

## **Conservative equations and analogy using generalized functions**

• Equations of conservation of mass and momentum can be rewritten as:

$$\frac{\partial(\rho'H)}{\partial t} + \frac{\partial(\rho v_i H)}{\partial x_i} = \rho_0 \left( \mathbf{v} \cdot \nabla F \right) \boldsymbol{\delta}(F) = \rho_0 V_n \, \boldsymbol{\delta}(F)$$
$$\frac{\partial(\rho v_i H)}{\partial t} + \frac{\partial}{\partial x_j} \left[ \left( \rho v_i v_j + p \, \boldsymbol{\delta}_{ij} + \sigma_{ij} \right) H \right] = \left( p \, \boldsymbol{\delta}_{ij} + \sigma_{ij} \right) \nabla F \, \boldsymbol{\delta}(F)$$

• The analogy becomes:

$$\frac{\partial^2(\rho'H)}{\partial t^2} - c_0^2 \frac{\partial^2(\rho'H)}{\partial x_i^2} = \frac{\partial^2}{\partial x_i \partial x_j} (T_{ij}H) - \frac{\partial}{\partial x_i} \left[ \left( p \, \mathbf{\delta}_{ij} + \sigma_{ij} \right) \nabla F \, \mathbf{\delta}(F) \right] + \frac{\partial}{\partial t} (\rho_0 V_n \, \mathbf{\delta}(F)) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F) \right) + \frac{\partial}{\partial t} \left( \rho_0 V_n \, \mathbf{\delta}(F)$$

## **Integral solution**

• Using the free-field Green's function:

$$\rho'(\mathbf{x},t) = \frac{\partial^2}{\partial x_i \partial x_j} \int_{-\infty}^t \iiint_V \frac{\delta(t-\tau - |\mathbf{x}-\mathbf{y}|/c_0)}{4\pi c_0^2 |\mathbf{x}-\mathbf{y}|} T_{ij}(\mathbf{y},\tau) \,\mathrm{d}^3 \mathbf{y} \,\mathrm{d}\tau$$
$$- \frac{\partial}{\partial x_i} \int_{-\infty}^t \iiint_V \frac{\delta(t-\tau - |\mathbf{x}-\mathbf{y}|/c_0)}{4\pi c_0^2 |\mathbf{x}-\mathbf{y}|} \left[ p \, \delta_{ij} + \sigma_{ij} \right] (\mathbf{y},\tau) \, n_j \,\mathrm{d}^2 \mathbf{y} \,\mathrm{d}\tau$$
$$+ \frac{\partial}{\partial t} \int_{-\infty}^t \iiint_{\partial V} \frac{\delta(t-\tau - |\mathbf{x}-\mathbf{y}|/c_0)}{4\pi c_0^2 |\mathbf{x}-\mathbf{y}|} \rho_0 V_n(\mathbf{y},\tau) \,\mathrm{d}^2 \mathbf{y} \,\mathrm{d}\tau$$

- More practical to have the source described in a moving coordinate system  $\eta$  attached to the body.
- Retarded time equation:
- Dirac function property:

$$g(t^*, t, \mathbf{x}, \boldsymbol{\eta}) \equiv t - t^* - \frac{|\mathbf{x} - \mathbf{y}(\boldsymbol{\eta}, t^*)|}{c_0} = 0$$
$$\int_{-\infty}^{\infty} \delta(h(\xi)) \ f(\xi) \,\mathrm{d}\xi = \sum_i \frac{f(\xi_i)}{|h'(\xi_i)|}, \quad h(\xi_i) = 0$$

## **Doppler effects**

+

• Applied to the quadrupolar component:

$$\int_{-\infty}^{t} \iiint_{V_{\eta}} \frac{\delta(g(\tau, t, \mathbf{x}, \boldsymbol{\eta}))}{4\pi c_{0}^{2} |\mathbf{x} - \mathbf{y}(\boldsymbol{\eta}, \tau)|} T_{ij} \,\mathrm{d}^{3}\boldsymbol{\eta} \,\mathrm{d}\tau = \frac{1}{4\pi c_{0}^{2}} \iiint_{V_{\eta}} \left[ \frac{T_{ij}}{R |1 - \mathbf{M}.\mathbf{R}/R|} \right] \,\mathrm{d}^{3}\boldsymbol{\eta}$$

 ${f M}$  : vector Mach number  $1-{f M}.{f R}/R$  : Doppler factor

• Final solution: 
$$\rho'(\mathbf{x},t) = \frac{1}{4\pi c_0^2} \frac{\partial^2}{\partial x_i \partial x_j} \iiint_{V_{\eta}} \left[ \frac{T_{ij}}{R |1 - \mathbf{M}.\mathbf{R}/R|} \right] d^3 \boldsymbol{\eta}$$
  
 $- \frac{1}{4\pi c_0^2} \frac{\partial}{\partial x_i} \iint_{\partial V_{\eta}} \left[ \frac{(p \, \boldsymbol{\delta}_{ij} + \sigma_{ij}) \, n_j}{R |1 - \mathbf{M}.\mathbf{R}/R|} \right] d^2 \boldsymbol{\eta}$   
 $+ \frac{1}{4\pi c_0^2} \frac{\partial}{\partial t} \iint_{\partial V_{\eta}} \left[ \frac{\rho_0 V_n}{R |1 - \mathbf{M}.\mathbf{R}/R|} \right] d^2 \boldsymbol{\eta}$ 

- The flow intrinsic features (flow separation, turbulent transition, ...) are expressed in the frame of reference attached to the moving axes.
- The Doppler effects (convective amplification and frequency shift) are given by the motion of the sources in the fixed coordinate system.

## **Effect of relative motion**



Fixed monopole



(source:

Wikipedia)

Monopole convected at M = 0.7

## **Doppler amplification**

$$\begin{split} \Delta \varphi - \frac{1}{c_0^2} \frac{\partial^2 \varphi}{\partial t^2} &= S(\mathbf{x}, t) \qquad S(\mathbf{y}, \tau) = -q(\tau) \,\delta(\mathbf{y} - \mathbf{U}_0 \tau) \\ \varphi(\mathbf{x}, t) &= \int_{-\infty}^{\infty} \int_{V} q(\tau) \, \frac{\delta(\tau - t + |\mathbf{x} - \mathbf{y}|/c_0)}{4\pi |\mathbf{x} - \mathbf{y}|} \,\delta(\mathbf{y} - \mathbf{U}_0 \tau) \,\mathrm{d}^3 \mathbf{y} \mathrm{d} \tau \\ \int_{-\infty}^{\infty} f(\xi') \delta(g(\xi')) \,\mathrm{d} \xi' &= \sum_{j} \frac{f(\xi_j)}{\left| \frac{\partial g}{\partial \xi}(\xi_j) \right|} \\ g(\tau) &\equiv \tau - t + |\mathbf{x} - \mathbf{y}(\tau)|/c_0 = 0 \qquad R_i \bigwedge_{i \neq 0} R_i \overset{R}{\bigwedge} d_i = 0 \end{split}$$

 $\theta$ 

S(t)

 $\theta$ .

 $S(t_i)$ 

 $\mathbf{U}_0$ 

$$\varphi(\mathbf{x}, t) = \frac{1}{4\pi} \sum_{j} \frac{q(\tau_j)}{R_j [1 - M_0 \cos \theta_j]}$$

Doppler factor: amplitude modulation and directivity

## **Doppler frequency shift**

$$\begin{split} q(\tau) &= \hat{q} \, \mathrm{e}^{\mathrm{i}\omega\tau} \\ \varphi(\mathbf{x},t) &= \frac{\hat{q}}{4\pi} \frac{\mathrm{e}^{\mathrm{i}\omega(t-R_1(t)/c_0)}}{R_1(1-M_0\cos\theta_1)} \\ \frac{R_1(t)}{c_0} &\sim \frac{R_1(t_e)}{c_0} + \frac{1}{c_0} \frac{\mathrm{d}R_1}{\mathrm{d}t} \Big|_{t_e} (t-t_e) + \dots \\ \frac{\mathrm{d}R_1}{\mathrm{d}t} &= -\frac{M_0\cos\theta_1}{1-M_0\cos\theta_1} \\ \end{split}$$
Phase factor :  $\mathrm{e}^{\mathrm{i}\omega t/(1-M_0\cos\theta_1(t_e))}$ 
Modified frequency :  $\frac{\omega}{1-M_0\cos\theta_1(t_e)}$ 
Doppler factor: frequency shift

The Doppler factor accounts for all amplitude modulation and frequency shift effects; the source unsteadiness can be described in a local (moving) coordinate system attached to the moving body.

## Thickness, loading, turbulence noise



• Loading noise: steady and unsteady

Thickness noise:

 Turbulence noise: same scaling, relative to unsteady loading noise, as for the motion loading noise → negligible as well

## At low Mach numbers, and for thin rotor/stator blades/vanes, the unsteady loading noise dominates the sound production.

## Loading noise mechanisms



## **Viscous and potential interactions**



Stator vanes: varying inlet velocity angle and magnitude



Rotor blades: varying outlet velocity angle and magnitude

## Viscous interaction: tonal and broadband noise



## **Tonal and broadband noise**



Kucukcoskun, K., Christophe, J., Schram, C., Holmberg, M., ISROMAC15, 2014.

## **Rotating point force**

• FW-H analogy in time domain:

$$\rho'(\mathbf{x},t) = \underbrace{\int_{-\infty}^{t} \int_{S(\tau)} \frac{\partial G}{\partial y_i} f_i \,\mathrm{d}^2 \mathbf{y} \,\mathrm{d}\tau}_{S(\tau)} + \underbrace{\int_{-\infty}^{t} \int_{V(\tau)} \frac{\partial^2 G}{\partial y_i \partial y_j} T_{ij} \,\mathrm{d}^3 \mathbf{y} \,\mathrm{d}\tau}_{V(\tau)} + \underbrace{\int_{-\infty}^{t} \int_{S(\tau)} \frac{\partial G}{\partial \tau} \rho_0 V_n \,\mathrm{d}^2 \mathbf{y} \,\mathrm{d}\tau}_{S(\tau)}$$

loading noise

quadrupolar noise

thickness noise

 Using the free field Green's function, and for a compact source:

$$\begin{split} \rho'(\mathbf{x},t) &\sim -\frac{1}{4\pi c_0^2} \frac{\partial}{\partial x_i} \int_{S(\tau_0)} \left[ \frac{f_i}{R|1 - \mathbf{M}.\mathbf{R}/R|} \right]_{\tau^*} \mathrm{d}^2 \boldsymbol{\zeta} \\ &\sim -\frac{1}{4\pi c_0^2} \frac{\partial}{\partial x_i} \left[ \frac{F_i}{RD} \right] \end{split}$$

• In the Fourier domain:

$$\rho(\mathbf{x},\omega) = \frac{\mathrm{i}k}{8\pi^2 c_0^2} \int_{-\infty}^{\infty} \frac{\mathbf{F}.\mathbf{R}}{R^2} \left(1 + \frac{1}{\mathrm{i}kR}\right) \,\mathrm{e}^{-\mathrm{i}\omega(\tau + R/c_0)} \,\mathrm{d}\tau$$

$$\uparrow$$
*Near-field*





### Doppler effect $\rightarrow$ summation over the BLHs



## **Summary**

- Aeroacoustical analogies allow extracting a maximum of acoustical information from a given description of the flow field
- Assuming a decoupling between the sound production and propagation, the analogies provide an explicit integral solution for the acoustical field at the listener position
  - Improves numerical robustness
  - Permits drawing scaling laws
- BUT: one has to make approximations and choices!
  - Acoustical variable (e.g. isothermal noise vs combustion noise)
  - Source term formulation (e.g. Lighthill's analogy vs Vortex Sound Theory)
- Some formulations make the dominant character of the source appear more explicitly, and allow making useful approximations.
- Without approximations, the analogy is useless!

## A few references

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- And of course: the VKI Lecture Series...